# ON THE CURVATURE TENSOR OF A SEMI-SYMMETRIC SEMI-METRIC CONNECTION

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ABSTRACT. A semi-symmetric semi-mertic connection has been introduced by Barua and Mukhopadhyay and the curvature tensor of such a connection has been deduced by them. The nature of the Riemann curvature tensor has been studied after putting some restrictions on the curvature tensor of the semi-symmetric semi-metric connection.

#### 1. INTRODUCTION

A semi-symmetric semi-metric connection  $\overline{\nabla}$  on a Riemannian manifold is defined by [1].

 $(\overline{\nabla}_X g)$  (Y, Z) = 2  $\alpha$  (X) g (Y, Z) -  $\alpha$  (Y) g (X, Z) -  $\alpha$  (Z) g (Y, X)... ... (1.1) where g is the Riemann metric on the manifold and  $\alpha$  is a differentiable 1-form, called the associated 1-form. The torsion tensor of the connection  $\overline{\nabla}$  is given by T (y, z) =  $\alpha$  (z) y -  $\alpha$  (y) z ... ... (1.2)

It is known that the connection  $\overline{\nabla}$  is of the form [2].

 $\overline{\nabla}_{Y}Z = \nabla_{Y}Z - \alpha (Y)Z + g (Y, Z)A \qquad \dots \dots (1.3)$ 

where  $\nabla$  is the Riemann connection and A is the associated vectorfield defined by g (A, X) =  $\alpha$  (X) ...... (1.4)

The curvature tensor  $\overline{R}(X, Y)$  Z of  $\overline{\nabla}$  is given by

 $\overline{R}$  (X, Y)Z = R (X, Y) Z - 2d $\alpha$  (X, Y) Z + g (Y, Z) LX - g (X, Z) LY... (1.5) where LX =  $\nabla_{x}A$  +  $\alpha$  (X)A and R (X, Y) Z is the Riemann curvature tensor.

Defining K (X, Y, Z, U) = g (R (X, Y) Z, U) and  $\overline{K}$  (X, Y, Z, U) = g ( $\overline{R}$  (X, Y) Z, U), we get

 $\overline{K}$  (X, Y, Z, U) = K (X, Y, Z, U) – 2d $\alpha$  (X, Y) g (Z, U) + g (Y, Z)  $\lambda$  (X, U) -g (X, Z)  $\lambda$  (Y, U) ... ... (1.6)

where

$$\lambda(X, U) = g(LX, U) = (\nabla_X \alpha)(U) + \alpha(X) \alpha(U)$$
 .....(1.7)

It can be seen from (1.6) that  $\overline{K}$  (X, Y, Z, U) +  $\overline{K}$  (Y, X, Z, U) = 0. But the other three identities, satisfied by K (X, Y, Z, U) are not, in general, satisfied by  $\overline{K}$  (X, Y, Z, U).

By direct calculation follows that-

$$\overline{K}$$
 (X, Y, Z, U) +  $\overline{K}$  (Y, Z, X, U) +  $\overline{K}$  (Z, X, Y, U) = 0 if and only if  $d\alpha = 0$ . Then (1.6) reduces to

$$\overline{K}$$
 (X, Y, Z, U) = K (X, Y, Z, U) + g (Y, Z)  $\lambda$  (X, U) - g (X, Z)  $\lambda$  (Y, U)..... (1.8) and  $\lambda$  (X, U) =  $\lambda$  (U, X).

Throughout this paper we have considered  $d\alpha = 0$ .

#### 2. THE OTHER TWO IDENTITIES

It is known that the Riemann curvature tensor K (X, Y, Z, U) satisfies. K (X, Y, Z, U) + K (X, Y, U, Z) = O and K (X, Y, Z, U) = K (Z, U, X, Y)...... (2.1) which are, in general, not satisfied by  $\overline{K}$  (X, Y, Z, U).

Let  $\overline{K}$  (X, Y, Z, U) +  $\overline{K}$  (X, Y, U, Z) = O. Then, g (Y, Z)  $\lambda$  (X,U) - g (X, Z)  $\lambda$  (Y, U) + g (Y, U)  $\lambda$  (X, Z) - g (X, U)  $\lambda$  (Y, Z) = 0 Summing for Y and Z, we find

$$\lambda(X, U) = \frac{tr\lambda}{n}g(X, U)$$
 .....(2.2)

The same result holds, if  $\overline{K}$  (X, Y, Z, U) =  $\overline{K}$  (Z, U, X, Y)

On the other hand, if (2. 2) holds, then the two identities in (2.1) are satisfied. In this case—

$$\overline{K}$$
 (X, Y, Z, U) = K (X, Y, Z, U) +  $\frac{tr\lambda}{n}$  {g (Y, Z) g (X, U) - g (X, Z) g (Y, U)} .....(2.3)

If now,  $\overline{K}$  (X, Y, Z, U) vanishes identically, then,

$$K (X, Y, Z, U) = \frac{tr\lambda}{n} \{g (X, Z) g (Y, U) - g (X, U) g (Y, Z)\} \dots \dots (2.4)$$

**Theorem 2.1.** If the curvature tensor of a semi-symmetric semi-metric connection vanishes identically, then the manifold is of constant curvature.

## 3. FIRST SET OF RESTRICTIONS ON $\overline{R}$ (X, Y)Z AND T (Y,Z)

Let the curvature tensor R (X, Y) Z and the torsion tensor T (X, Z) of the semisymmetric semi-metric connection satisfy the relations,

$$\alpha (\overline{R}(X, Y)Z) = 0 \qquad \dots \dots (3.1)$$

and 
$$\overline{R}$$
 (X, Y) oT = O ..... (3.2)

It is known that [3]

 $(R(X, Y)T)(U, V) = \overline{R}(X, Y) T(U,V) - T(\overline{R}(X, Y) U, V) - T(U, \overline{R}(X, Y)V) (\overline{\nabla}_{\tau(X,Y)}T)$  (U,V)

In view of (3.1) and (3.2), the above is equivalent to

$$(\overline{\nabla}_{\tau(X,Y)}T) (U,V) = O \qquad \dots \dots (3.3)$$

Now, using (1.3), we get

$$(\overline{\nabla}_{x}T)$$
 (U,V) =  $\{\lambda(X, V) - ag(X, V)\}$  U -  $\{\lambda(X,U) - ag(X,U)\}$  V .....(3.4) where a = g (A, A) =  $\alpha$  (A). Substituting from (3. 4) in (3. 3) we get

$$\alpha$$
 (X) [{  $\lambda$ (Y, V) - ag (Y, V)} U - {  $\lambda$  (Y, U) - ag (Y, U)} V]

= 
$$\alpha$$
 (Y) [{  $\lambda$ (X, V) - ag (X, V)} U - {  $\lambda$  (X, U) - ag (X, U)} V]

from which, we get

$$\alpha$$
 (X) [{  $\lambda$ (Y, V) - ag (Y, V)} =  $\alpha$  (Y) - {  $\lambda$  (X, V) - ag (X, V)}

Putting Y = A, we get form the last equation

$$\alpha(X) \{ \lambda(A, V) - a \alpha (V) \} = a \{ \lambda (X, V) - ag (X, V) \}$$
 ..... (3, 5)

Again, putting V = A in (3.5), we get

$$\lambda (X, A) = \frac{\lambda(A, A)}{a} \alpha (X) \qquad \dots \dots (3.6)$$

Substituting (3.6) in (3.5), we get

$$\lambda$$
 (X, V) =  $\beta$   $\alpha$  (X)  $\alpha$ (V) + ag (X, V) ..... (3.7) where

$$\beta = \frac{\lambda(A, A)}{a^2} - 1 \qquad \dots \dots (3.8)$$

In view of (3. 7), we get from (1. 8)

$$\overline{K}$$
 (X, Y, Z, U) = K (X, Y, Z, U) + a { g (Y, Z) g (X, U) - g (X, Z) g (Y, U)} +  $\beta$  { g (Y, Z)  $\alpha$  (X)  $\alpha$  (U) - g (X, Z)  $\alpha$  (Y)  $\alpha$  (U)} ..... (3.9)

From (3.8) we find  $\beta$  = 0 if and only if A is a geodesic congruence. If moreover, K (X, Y, Z, U) vanishes identically, then (3.9) reduced to-

$$\overline{K}$$
 (X, Y, Z, U) = a {g (Y, Z) g (X, U) - g (X, Z) g (Y, U)} ...... (3.10)  
Theorem 3.1 If the curvature tensor of a semi-symmetric semi-metric connection es (3.1) and (3.2) then it is given by (3.2)

satisfies (3.1) and (3.2), then it is given by (3.9).

Theorem 3.2 If on a flat manifold the associated vector field of a semi-symmetric semi-metric connection is a geodesic congruence then the manifold is of constant curvature with respect to this connection.

### 4. SECOND SET OF RESTRICTIONS ON $\overline{R}$ (X, Y) Z AND T (Y, Z)

Let the curvature tensor  $\overline{K}$  (X, Y, Z, U) and the torsion tensor T (Y, Z) satisfy,

K (X, Y, Z, U) = g (Y, U) { 
$$\sigma$$
 (X)  $\alpha$  (Z) +  $\sigma$  (Z)  $\alpha$  (X)}  
- g (X, U) {  $\sigma$  (Y)  $\alpha$  (Z) +  $\sigma$  (Z)  $\alpha$  (Y)} ...... (4.1)

and 
$$(\nabla_{\mathbf{x}} \mathbf{T}) (\mathbf{Y}, \mathbf{Z}) = \sigma (\mathbf{X}) \mathbf{T} (\mathbf{Y}, \mathbf{Z})$$
 ...... (4.2)

where  $\sigma$  is a differentiable 1-form.

From (4.2) we get

$$(\nabla_{\mathbf{x}} \ \alpha) \ (\mathbf{Z}) = \sigma \ (\mathbf{X}) \ \alpha \ (\mathbf{Z}) \qquad \dots \dots (4.3)$$

and 
$$(\nabla_{\mathbf{x}} \mathbf{A}) = \sigma(\mathbf{X}) \mathbf{A}$$
 .....(4.5)

**Therefore** 

$$\lambda$$
 (X, Z) =  $\sigma$  (X)  $\alpha$  (Z) +  $\alpha$  (X)  $\alpha$  (Z) ...... (4.5)

Again—

 $\lambda$  (X, Z) =  $\lambda$  (Z, X) implies

$$\sigma$$
 (X) = t  $\alpha$  (X), t =  $\frac{\sigma(A)}{\alpha(A)}$  ... ... (4.6)

Hence 
$$\lambda$$
 (X, Z) = (t + 1)  $\alpha$  (X)  $\alpha$  (Z) .....(4.7) Using (4.7) in (1.8) we get

2t {g (Y, U)  $\alpha$  (X)  $\alpha$  (Z) -g (X, U)  $\alpha$  (Y)  $\alpha$  (Z)}

= 
$$K$$
 (X, Y, Z, U) + (t + 1) {g (Y, Z)  $\alpha$  (X)  $\alpha$  (U) -g (X, Z)  $\alpha$  (Y)  $\alpha$  (U)}..... (4,8)

t = 1, we find  $\sigma(X) = \alpha(X)$  and

$$\begin{array}{l} \mathsf{K} \ \ (\mathsf{X},\ \mathsf{Y},\ \mathsf{Z},\ \mathsf{U}) \ = \ 2 \ \{\mathsf{g} \ \ (\mathsf{Y},\ \mathsf{U}) \ \alpha \ (\mathsf{X}) \ \alpha \ (\mathsf{Z}) \ - \ \mathsf{g} \ (\mathsf{X},\ \mathsf{U}) \ \alpha \ (\mathsf{Y}) \ \alpha \ (\mathsf{Z}) \\ + \ \mathsf{g} \ \ (\mathsf{X},\ \mathsf{Z}) \ \alpha \ (\mathsf{Y}) \ \alpha \ (\mathsf{U}) \ - \ \mathsf{g} \ (\mathsf{Y},\ \mathsf{Z}) \ \alpha \ (\mathsf{X}) \ \alpha \ (\mathsf{U})\} \end{array} \qquad \dots \dots (4.9)$$

Hence the manifold is of almost constant curvature [4].

**Theorem 4.1.** If the curvature tensor of a semi-symmetric semi-metric connection satisfies (4.1) and the torsion tensor is recurrent, then the 1-form of recurrence must be a scalar multiple of the associated 1-form. In this case the associated vectorfield is also recurrent.

**Theorem 4.2.** If the curvature tensor of a semi-symmeteric semi-metric connection satisfies (4.1) and the torsion tensor is recurrent, the 1-form of recurrence being the associated 1-form, then the manifold is of almost constant curvature.

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